

# On the Relation of Variability Modeling Languages and Non-Functional Properties

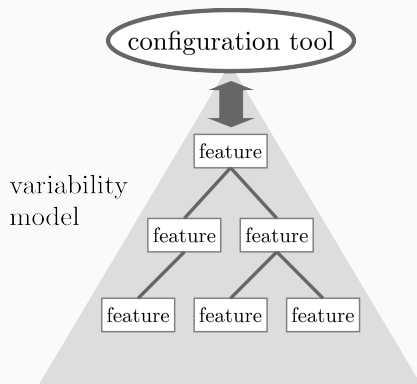
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Universität Osnabrück / Arbeitsgruppe Eingebettete Softwaresysteme



## Option

- (16) Batch Size
- ▼ Hardware Platform
  - Coral EdgeTPU Dev Board
  - i.MX EVK
  - Jetson Nano
  - Jetson Xavier NX
  - ⊙ Raspberry Pi 4 B (aarch64)
- ▶ NN Framework
- ▶ Task (NEW)
- ▶ NN Architecture
- ▶ TFLite Optimizations (NEW)

Variability models → interactive software product line configuration



## Configuration

Cost: 60 €

Inference Time: 532 ms

Memory Footprint: 122 MB

Model Size: 4 MB

Throughput: 32.1 FPS

Batch Size

Hardware Platform

NN Framework

Task (NEW)

NN Architecture

Quantization (NEW)

### hw\_platform

Coral EdgeTPU Dev Board ☐ +100 € -12.4 FPS

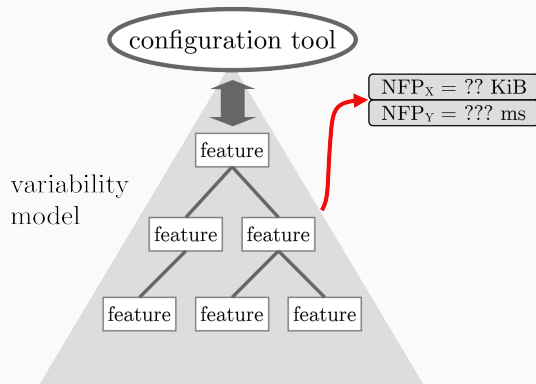
i.MX EVK ☐ +440 € +88.5 FPS

Jetson Nano ☐ +57 € -1.2 FPS

Jetson Xavier NX ☐ +420 € +14.2 FPS

Raspberry Pi 4 B (aarch64) ☒

Non-functional property (NFP) models → performance-aware configuration



How to add non-functional properties to a variability model?

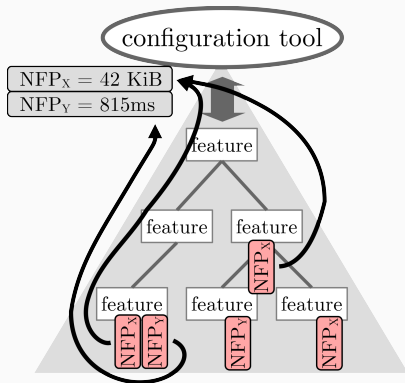


1 Approaches

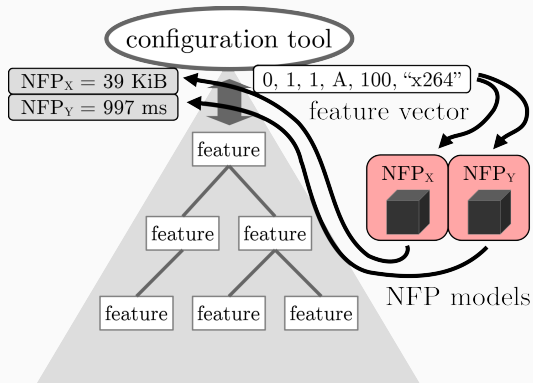
2 Analysis

3 Evaluation

4 Conclusion



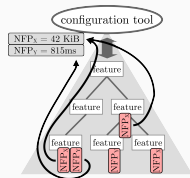
**Integrated NFP Model**



**Separate NFP Model**



- NFPs are **attributes** of individual **features**
- Aggregation functions define NFP of the complete product





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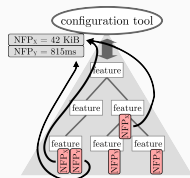
E.g. ClaferMoo [Ola+12]

EdgeTPU : HWFeature [cost = 160]

RasPi4 : HWFeature [cost = 60]

Battery : HWFeature [cost = 50]

totalCost : integer [ totalCost = sum HWFeature.cost ]







- NFPs are **attributes** of individual **features**
- Aggregation functions define NFP of the complete product

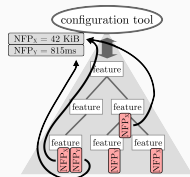
E.g. TVL [Bou+10]

EdgeTPU {int cost is 160;}

RasPi4 {int cost is 60;}

Battery {int cost is 50;}

EdgeML {int cost is sum(selectedChildren.cost)}





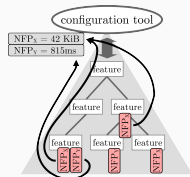
- NFPs are **attributes** of individual **features**
- Aggregation functions define NFP of the complete product

E.g. UVL [Sun+21]

EdgeTPU {cost 160}

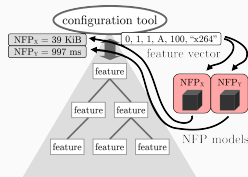
RasPi4 {cost 60}

Battery {cost 50}





- **Feature vector**  $\vec{x}$  describes product configuration
- Calculate NFP  $y$  using separate model function  $f : \vec{x} \mapsto y$



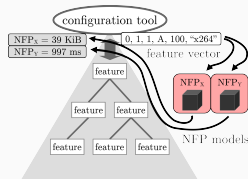


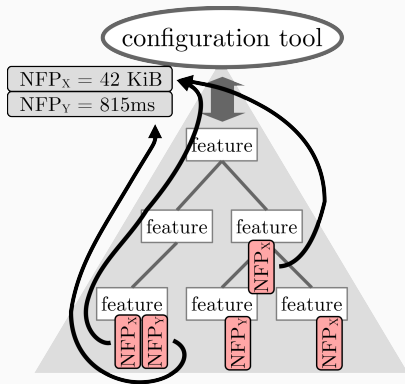
- **Feature vector**  $\vec{x}$  describes product configuration
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E.g.  $\vec{x} = (x_{\text{HW}}, x_{\text{Bat}}) \in \{\{\text{EdgeTPU}, \text{RasPi4}\}, \{0, 1\}\}$

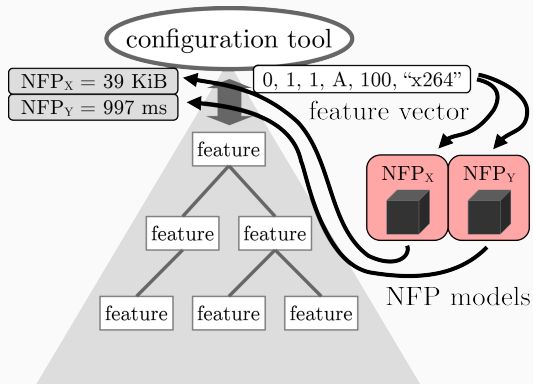
$$\text{cost}(\vec{x}) = 50 \cdot x_{\text{Bat}} + \begin{cases} 160 & x_{\text{HW}} = \text{EdgeTPU} \\ 60 & x_{\text{HW}} = \text{RasPi4} \end{cases}$$

Arbitrary functions can be used, e.g. regression trees or neural networks





Integrated NFP Model



Separate NFP Model

**Should NFP models be part of the variability model?**



1 Approaches

2 Analysis

3 Evaluation

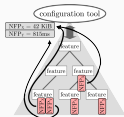
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Annotation Process

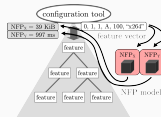
Complexity  
Expressiveness  
Maintenance  
Modularity

Accuracy



## Integrated NFP Model

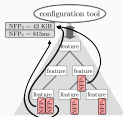
- Manual annotation
- Benchmarks → model training



## Separate NFP Model

- Manual annotation
- Benchmarks → model training

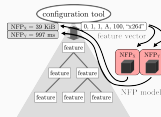




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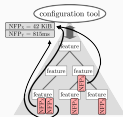
- ✓ Manual annotation
- (✓) Benchmarks → model training

size = sum feat.size  
\* (debug ? 1.2 : 1)

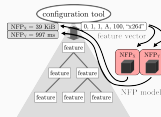


## Separate NFP Model

- (✓) Manual annotation
  - ✓ Benchmarks → model training
- E.g. CART, XGBoost, neural networks



**Integrated** NFP Model



**Separate** NFP Model

✓ Manual annotation

(✓) Benchmarks → model training

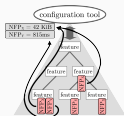
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(✓) Manual annotation

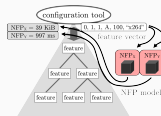
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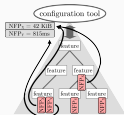
## Integrated NFP Model

- Defined by modeling language
- Typically limited to
  - feature-wise annotations
  - feature interaction
  - aggregate functions



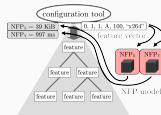
## Separate NFP Model

- Chosen as suitable
- Near arbitrary, e.g.
  - feature-wise annotations
  - regression trees
  - neural networks



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Features may interact with each other (→ not independent)

<b>DB</b>		<b>Debug</b>	<b>Safety</b>
–	172 kB	+ 45 kB	+ 18 kB
<b>Multi</b>	+ 20 kB		
<b>WAL</b>	+ 32 kB		



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- Handled in variability modeling languages by *feature interaction* [Sie+12]
  - Check each feature pair  $A, B$  for interaction (domain expert or benchmarks)
  - If yes: add feature  $AB$  with  $AB \Leftrightarrow A \wedge B$  to variability model
  - E.g.: (Multi, Debug) = 3 kB; (Multi, Safety) = 11 kB; (WAL, Debug) = 4 kB
  - Can be extended for more complex interactions (e.g.  $ABCD$ )



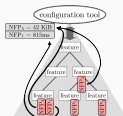
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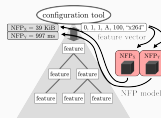
- Separate NFP models can automatically learn about this





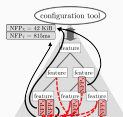
## Integrated NFP Model

- Feature-wise annotations:  
simple → easy to understand



## Separate NFP Model

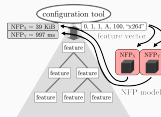
- Depends on model type
- XGBoost, NN: hard to grasp



**Integrated** NFP Model

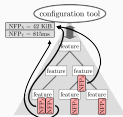
- Feature-wise annotations:  
simple → easy to understand
- Feature interactions clutter the  
model

≈



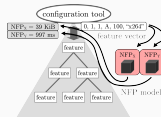
**Separate** NFP Model

- Depends on model type
- XGBoost, NN: hard to grasp
- Regression model trees:  
Expressive and  
understandable [FS22]



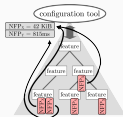
## Integrated NFP Model

- Method defined by variability modeling language
- No separation of concerns: NFP attributes become useless after implementation changes



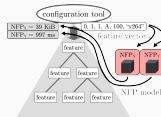
## Separate NFP Model

- Method can be changed at will
- Implementation change → new NFP model or transfer learning [Jam+18]



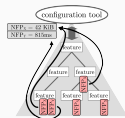
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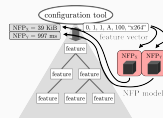
## Separate NFP Model

- Method can be changed at will
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## Integrated NFP Model

- Annotation by domain expert
- Clear feature  $\leftrightarrow$  NFP relation
- cross-cutting concerns present  
→ inaccurate or complex



## Separate NFP Model

- Automated generation
- Separation of concerns
- Arbitrary model complexity  
→ problem-specific approaches



1 Approaches

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**3 Evaluation**

4 Conclusion

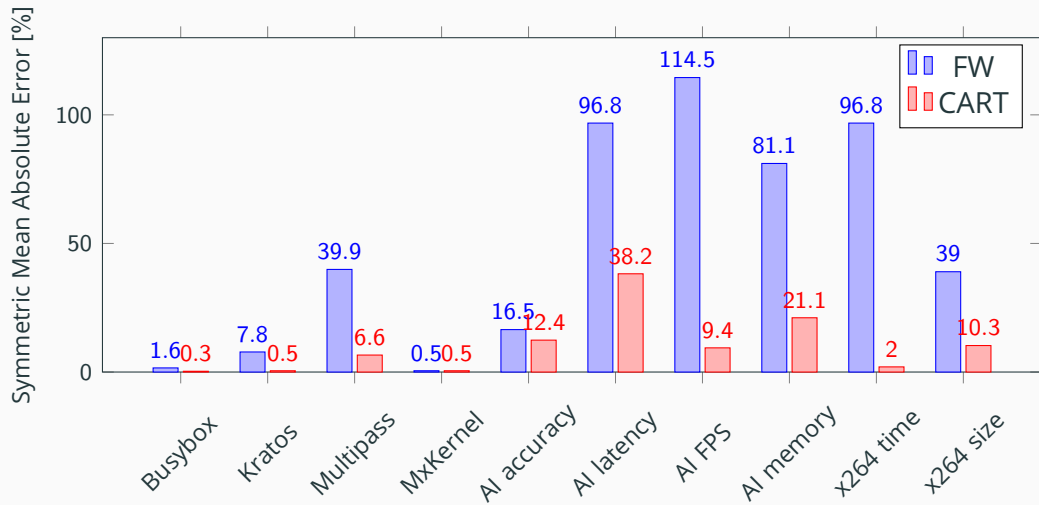


- Integrated model: Feature-wise annotations (FW)

$$\beta_0 + \beta_1 x_1 + \beta_2 x_2 + \dots + \beta_n x_n$$

- Separate model: Classification and Regression Trees (CART) [Bre+84]  
Go-to approach for data-efficient NFP model generation [Guo+18]
- Six product lines:
  - **busybox** multi-call binary → Binary size
  - **Kratos, Multipass, MxKernel** research OSes → ROM usage
  - **resKIL** embedded AI product line → accuracy, latency, throughput, memory
  - **x264** video codec → encoding duration and file size

# Model Error (10-fold cross validation)







- Decision tree structure naturally captures dependencies between features
- Higher model accuracy

# Advantages of External Models



- Decision tree structure naturally captures dependencies between features
- Higher model accuracy



- Influential features located close to the root
- Understandable performance model

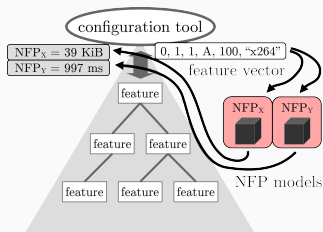


1 Approaches

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**4 Conclusion**



## Separate NFP Model

- Opinion: variability models should **not** incorporate NFP-related concerns
- Instead:
  - Formalize configurations / products as **feature vectors**
  - Use configuration tool to link variability and NFP models



- [Bou+10] Quentin Boucher et al. **“Introducing TVL, a text-based feature modelling language”**. In: Proceedings of the Fourth International Workshop on Variability Modelling of Software-intensive Systems (VaMoS’10). 2010, pp. 159–162.
- [Bre+84] Leo Breiman et al. **Classification and regression trees**. Routledge, 1984. DOI: 10.1201/9781315139470.
- [FS22] Birte Friesel and Olaf Spinczyk. **“Regression Model Trees: Compact Energy Models for Complex IoT Devices”**. In: Proceedings of the Workshop on Benchmarking Cyber-Physical Systems and Internet of Things. CPS-IoTBench ’22. IEEE, May 2022, pp. 1–6. DOI: 10.1109/CPS-IoTBench56135.2022.00007. URL: <https://ess.cs.uos.de/static/videos/cpsiotbench22-Friesel-RMT.mp4>.



- [Guo+18] Jianmei Guo et al. **“Data-Efficient Performance Learning for Configurable Systems”**. In: Empirical Softw. Engg. 23.3 (June 2018), pp. 1826–1867. ISSN: 1382-3256. DOI: 10.1007/s10664-017-9573-6. URL: <https://doi.org/10.1007/s10664-017-9573-6>.
- [Jam+18] Pooyan Jamshidi et al. **“Learning to Sample: Exploiting Similarities across Environments to Learn Performance Models for Configurable Systems”**. In: Proceedings of the 2018 26th ACM Joint Meeting on European Software Engineering Conference and Symposium on the Foundations of Software Engineering. ESEC/FSE 2018. Lake Buena Vista, FL, USA: Association for Computing Machinery, 2018, pp. 71–82. ISBN: 9781450355735. DOI: 10.1145/3236024.3236074. URL: <https://doi.org/10.1145/3236024.3236074>.



- [Ola+12] Rafael Olaechea et al. **“Modelling and Multi-Objective Optimization of Quality Attributes in Variability-Rich Software”**. In: Proceedings of the Fourth International Workshop on Nonfunctional System Properties in Domain Specific Modeling Languages. NFPinDSML '12. New York, NY, USA: Association for Computing Machinery, 2012. ISBN: 978-1-4503-1807-5. DOI: 10.1145/2420942.2420944. URL: <https://doi.org/10.1145/2420942.2420944>.
- [Sie+12] Norbert Siegmund et al. **“Predicting performance via automated feature-interaction detection”**. In: 2012 34th International Conference on Software Engineering (ICSE). 2012, pp. 167–177. DOI: 10.1109/ICSE.2012.6227196.



- [Sun+21] Chico Sundermann et al. **“Yet Another Textual Variability Language? A Community Effort towards a Unified Language”**. In: Proceedings of the 25th ACM International Systems and Software Product Line Conference - Volume A. New York, NY, USA: Association for Computing Machinery, 2021, pp. 136–147. ISBN: 9781450384698. URL: <https://doi.org/10.1145/3461001.3471145>.